

Affective Recommendation of Movies Based on Selected Connotative Features

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Abstract—The apparent difficulty in assessing emotions elicited by movies and the undeniable high variability in subjects' emotional responses to film content have been recently tackled by exploring film connotative properties: the set of shooting and editing conventions that help in transmitting meaning to the audience. Connotation provides an intermediate representation that exploits the objectivity of audiovisual descriptors to predict the subjective emotional reaction of single users. This is done without the need of registering users' physiological signals. It is not done by employing other people's highly variable emotional rates, but by relying on the intersubjectivity of connotative concepts and on the knowledge of user's reactions to similar stimuli. This paper extends previous work by extracting audiovisual and film grammar descriptors and, driven by users' rates on connotative properties, creates a shared framework where movie scenes are placed, compared, and recommended according to connotation. We evaluate the potential of the proposed system by asking users to assess the ability of connotation in suggesting film content able to target their affective requests.

Index Terms—Affective recommendation, video analysis.

I. INTRODUCTION

DURING the last few years, the technological evolution and the fast growth of social networks have been shaping a new generation of media consumers. Today, it is extremely easy to access private or shared repositories of multimedia content; as a consequence, the way people enjoy movies, music clips, or home-made videos has dramatically changed, thanks also to the introduction of video on-demand technologies.

In this scenario, a person that feels like watching a movie may rely on the suggestions of his or her group of friends, or on the opinions of a virtual community that shares the same interests. Alternatively, this person could also benefit from the help of a media recommender system with the ability to suggest video content on the basis of his or her user profile, social experience, relationships, and current affective state. The ability of tuning automatic systems according to the emotional state or wishes of users is receiving growing attention, due to the intriguing new possibilities that could be offered by applying affective computing techniques to multimedia systems [1].

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Psychologists have already investigated the emotion-eliciting properties of film media, both in terms of empathy with characters and situations, and in terms of the director's use of established film-making techniques that provide emotional cues. Regarding viewers' empathy, Tan [2] explained a universal affective response in terms of a witness effect in classical Hollywood films, wherein the viewer experiences the real emotions of being a part of the depicted events. Provided they are engaged with the media, viewers' responses are, therefore, a genuine reflection of the affective characterization of a scene.

According to Smith [3], it is not merely empathy with characters that provides the affective cues within film media. Indeed, film-makers make use of techniques of editing, musical scores, lighting, and other aspects of *mise-en-scene* to emphasize a particular emotional interpretation by the viewer. These aesthetic arcs within a film, referred to as *connotation*, plot a continuous path of affective communication, regardless of narrative or plot details, which influences how the meanings conveyed by the director are transmitted to persuade, convince, anger, inspire, or soothe the audience. In cinema as in the literature, we do not merely "read what we see," but connotation brings to our interpretation a range of pre-existing expectations, knowledge and shared experiences that shape the emotional meaning we take from what we see.

A. Paper Aims and Organization

The severe entanglement between connotation and emotions inspired authors to develop in [4] a space for affective description of movies through their connotative properties. In that work, authors tackled two main research questions.

- 1) To what extent can we trust emotions registered by other individuals and the content they recommend? The answer was: not much, since emotions are personal, and everyone reacts to any event or to media content in a way that depends on cultural, personal, past experiences and other, even short term, subjective factors. As a possible alternative, perceived connotative properties prove to be more intersubjectively shared than emotions [4].
- 2) Are connotative rates assigned by users more effective for recommending content than provided affective annotations? The outcome was that movie scenes different in content but similar in connotation likely elicit, in the same user, similar affective reactions. Therefore, using scene similarity based on connotative properties to recommend similar affective content to a single user

is more reliable than exploiting other users' emotional annotations [4].

In this paper, extending the work in [4], we target automatic recommendation of affective content based on audiovisual features. In particular, we investigate the following questions.

- 1) Can we predict connotative values from audiovisual features? By modeling the relationship between connotative rates assigned by users and selected audiovisual features, we are able to automatically predict connotative values as perceived by users, thus positioning scenes in the connotative space defined in [4].
- 2) Can we recommend affective content based on predicted values of connotation? Performed tests confirm that recommending movie scenes that are at minimum distance in the connotative space from a query one is an effective strategy for proposing similar emotional content. This verifies that the connotative space constitutes a valid intersubjective platform for affective comparison and recommendation of films.

As a first advantage with respect to the state of the art, the recommendation method here proposed reduces the problem of subjectivity of emotions connected to the use of other people's affective annotations. Since connotative properties are more agreed among people than their emotional reactions, connotation provides a more accurate recommendation method for targeting single users' affective requests.

Second, the proposed learning method that models how to translate low and mid-level properties of video into an intersubjective space for affective analysis of films constitutes a valid nonobtrusive alternative to established methods for performing research on emotions, such as users' self-reporting, monitoring of user's behavior, and neurophysiological signal recording (cited as in [5], on ascending scale of obtrusiveness).

This paper is organized as follows. Section II explores recent advances in affective video analysis and recaps previous findings and experiments in [4] preparatory to this paper. Section III presents the overall methodology, while Section IV describes the audiovisual features extracted to build models for the connotative dimensions. Section V sketches the algorithm used to select features among extracted candidates, which are then mapped onto connotative dimensions by means of the learning methods described in Section VI. Section VII first introduces a validation of the employed model by evaluating the ranking ability of the proposed method on recommendation lists against a ground truth; a user test then assesses performance and potentialities of the proposed framework for affective recommendation of movie scenes. Conclusions and future work are provided in Section VIII.

II. PREVIOUS WORK

Recent progress made in the development of affective systems, a well-detailed review of emotion theories, and methods for studying emotions in information science, information retrieval, and human-computer interaction, can be found in the notable work by Lopatovska and Arapakis [5]. Concerning multimedia affective content analysis, this research topic was not popular until a few years ago due to the difficulty in

defining objective methods for assessing the affective value of a video and for relating audiovisual descriptors with the emotional dimension of the audience. In this sense, the intuition of Hanjalic represents a breakthrough [6]; the affective dimension of media can be explored because of the expected mood, i.e., the set of emotions the film-maker intends to communicate when he or she produces the movie for a particular audience with a common cultural background. In a work co-authored with Xu [7], Hanjalic pioneers the affective analysis of video content through an approach based on direct mapping of specific video features onto the PA dimensions of the pleasure-arousal-dominance (PAD) emotional model [8]. They describe motion intensity, cut density, and sound energy as arousal primitives, defining an analytic time-dependent function for aggregating these properties along video frames. Though the mapping of video properties on a model intended for describing emotions (PAD) is inspired from the previous literature, it has not yet been thoroughly validated by psychological questionnaires or physiological measurements, which would be proper methods for assessing a time-dependent model.

To date, emotional characterization of videos has been mainly used to study a narrow set of situations, such as specific sporting events as in [9] or, most frequently, movies that belong to a particular genre such as horror movies, as in [10]. Extending this approach, Xu *et al.* [11] described emotional clustering of films for different genres, using averaged values of arousal and valence deduced from video parameters. Such a proposed framework performs better for action and horror films than for drama or comedy, a fact that authors attribute to the prominence of specific features in the first two genres.

Regarding movie scenes, Wang and Cheong [12] proposed to fuse audio and visual low-level features in a heterarchical manner in a high-dimensional space, and to extract from such a representation meaningful patterns by an inference SVM engine. They employed such an approach for probabilistic classification of Hollywood movie scenes into a finite set of affective categories. They also corroborated the view that audio cues are often more informative than visual ones with respect to affective content. In a later work [13], they proposed a motion-based approach combined with an inference engine to recognize different classes of film directing semantics, such as establishing shot, stationary shot and focus-in or focus-out, employed by directors to emotionally emphasize their work.

Irie *et al.*, by proposing a system for affective movie scene classification [14], tackled two main issues: 1) how to extract features that are strongly related to viewers' emotions and 2) how to map the extracted features onto emotion categories. They answered the first question by extracting bags of affective audio-visual words, while for the second one they created a "latent topic driving model" as an attempt for an intermediate representation where topics link emotions to events.

Recently, affective descriptions of multimedia items have also been applied to traditional recommender systems [15]. In [16], Tkalcic *et al.* proposed a framework that describes three stages (entry, consumption, and exit) at which emotions can be used to improve the quality of a recommender system. In a previous work [17], the same research group introduces the usage of metadata fields, containing emotional parameters to

200 increase the precision rate of content-based recommenders for
 201 images. By demonstrating that affective tags are more closely
 202 related to the user experience than generic descriptors, they
 203 improve the quality of recommendation by using metadata
 204 related to the aesthetic emotions perceived by users.

205 Content items can be labeled with affective metadata either
 206 explicitly, by asking the user to annotate the observed content
 207 with an affective label or, implicitly, by automatically detecting
 208 the user's emotional reaction (for a review on implicit human-
 209 centered tagging, please refer to [18]). Each of the two
 210 approaches has its pros and cons. Again, Tkalcic *et al.* [19]
 211 showed that content-based recommendation still works better
 212 when explicit labels are used, probably due to the still low
 213 accuracy of algorithms that detect affective responses. For this
 214 reason, research on improving affective implicit tagging is very
 215 active and opening up to a wide range of investigations.

216 Sicheng *et al.* [20], for example, proposed a video indexing
 217 and recommender system based on affective analysis of facial
 218 expressions. Users are monitored while watching content and
 219 their facial features extracted to infer a probable affective state;
 220 on this basis, an affective label is assigned to each movie
 221 segment for indexing and recommendation purposes.

222 Pupillary reflex, gaze distance, and EEG signals are used
 223 instead by Soleymani *et al.* in [21] to design an accurate
 224 classification protocol for recognizing emotions, attaining
 225 comparable performance to users' self-reporting. Although
 226 obtained on a fairly limited dataset of 20 video clips and
 227 24 participants, the promising accuracy seems to be easily
 228 scalable to a larger population. **In a similar fashion, SpudTV**
 229 **[22] within PetaMedia project develops** methods for affective
 230 implicit tagging of multimedia based on users' EEG signals
 231 and peripheral physiological responses.

232 Recommendation on mobile platforms for providing person-
 233 alized services that fit users' emotional states was explored
 234 by Kim and Choi in [23]. Their EmoSens system maintains
 235 affective scoring for various entities in a mobile device, such
 236 as applications, multimedia, and contacts. Scoring is based on
 237 particular patterns of device usage, which are inferred in a
 238 controlled experiment by collecting user feedback.

239 In the last few years, the problem of tailoring the recom-
 240 mendation experience to user-specific needs has become more
 241 evident. Arapakis *et al.* [24] indicated that adapting a general
 242 affective model to a specific user introduces a noticeable
 243 improvement in the system's ability to discriminate relevant
 244 from nonrelevant items. The problem of personal variability
 245 in subjects' emotional responses in the case of film content
 246 has been recently tackled also in our work in [4], which is
 247 summarized in the following paragraphs.

248 A. Connotative Space

249 In [4], we introduced the connotative space as a valid tool
 250 for representing the affective identity of a movie segment by
 251 those shooting and editing conventions that help in transmit-
 252 ting meaning to the audience. Inspired by similar spaces for
 253 industrial design [25], the connotative space accounts for a
 254 *natural* (N) dimension that splits the space into a passionate
 255 hemi-space, referred to as warm affections, and a reflective
 256 hemi-space that represents offish and cold feelings (associated

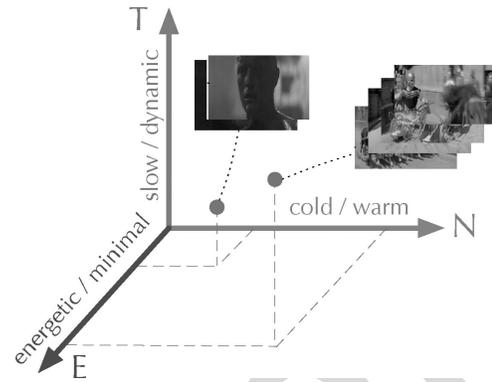


Fig. 1. Connotative space for affective analysis of movie scenes, as in [4].

dichotomy: warm versus cold). The *temporal* (T) axis char-
 257 characterizes the space into two other hemi-spaces, one related
 258 to high pace and activity and another describing an intrinsic
 259 attitude toward slow dynamics (dynamic versus slow). The
 260 *energetic* (E) axis identifies films with high impact in terms
 261 of affection and, conversely, minimal ones (energetic versus
 262 minimal).
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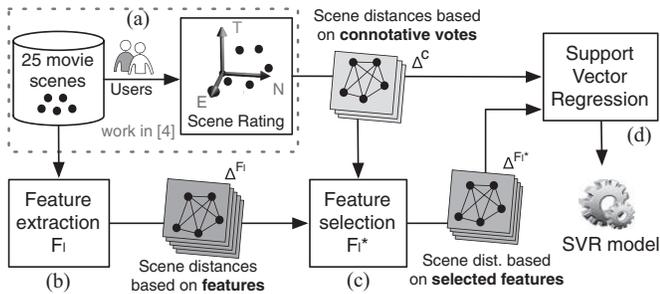
264 Unlike PAD representation, where each point describes *one*
 265 *emotion* in terms of pleasure, arousal and dominance, in the
 266 connotative space, a point (respectively a cloud) describes one
 267 (respectively more) *movie segment(s)* in terms of its (their)
 268 connotative properties, as shown in Fig. 1.

269 As a first advantage of using the connotative space, in [4]
 270 we showed that the level of agreement among users is higher
 271 when rating connotative properties of the movie rather than
 272 when they self-report their emotional responses to the same
 273 film content. The proposed space seems to fill the need for
 274 an intermediate semantic level of representation between low-
 275 level features and human emotions, and envisages an easy
 276 translation process of video low-level properties into interme-
 277 diate semantic concepts mostly agreeable among individuals.

278 The second main outcome provided by analysis in [4] shows
 279 how connotation is intrinsically linked to emotions. Specifi-
 280 cally, we proved that using connotation for recommending
 281 movies to a user whose emotional reactions to the same
 282 type of stimuli are known gives better results than exploiting
 283 emotional tags by other users. This implies that movie scenes
 284 sharing similar connotation are likely to elicit, in the same
 285 user, a similar affective reaction. As a consequence, we expect
 286 this space to help in reducing the semantic gap between video
 287 features and the affective sphere of individuals, thus avoiding
 288 the bridging at once process that often inaccurately maps low-
 289 level representations to human emotions.

290 III. OVERALL METHODOLOGY

291 While in [4] connotative rates were assigned by users, in this
 292 paper we aim to predict connotative values using audiovisual
 293 features only. Fig. 2 presents the modelling approach to
 294 establish a relation between connotative rates assigned by users
 295 and video characteristics. The predicted connotative values are
 296 then used for targeting recommendation of affective content in
 297 a user test, as described in Fig. 3. The descriptions of the main
 298 blocks follow.



AQ:1 Fig. 2. Diagram describing the modeling workflow.

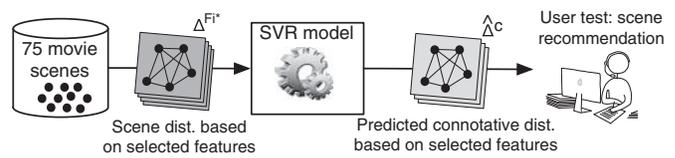


Fig. 3. User test diagram, performed in a recommendation scenario.

TABLE I
LIST OF EXTRACTED FEATURES

Visual	Dominant color, color layout, scalable color, color structure, color codebook, color energy, lighting key I, lighting key II, saturation*, motionDS*
Audio	Sound energy, low-energy ratio, zero-crossing rate*, spectral rolloff*, spectral centroid*, spectral flux*, MFCC*, subband distribution*, beat histogram, rhythmic strength
Grammar	Shot length, illuminant color, shot type transition rate

Descriptors with * are computed both in terms of average and standard deviation.

E. Scene Recommendation

Once the model is validated, we are able to predict connotative distances between movie scenes starting from distances based on selected features. As in Fig. 3, which describes the testing scenario, we compute interscene distances on selected features for 75 movie scenes. Then, by the learned SVR model, connotative distances are predicted as $\hat{\Delta}^C$. The final user test assesses the ability of the connotative space in recommending affective content: users choose a query item and annotate their emotional reactions to recommended scenes that are proposed since at low connotative distance from the query.

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IV. FEATURE EXTRACTION

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From movie scenes we extract features to describe professional video content: 12 visual descriptors, 16 audio features, and 3 related to the underlying film grammar, as listed in Table I. For each scene m_i and feature F_i , we gather feature values over time in histogram $H_i^{F_i}$. Considering that the system should easily include any new feature, we apply a common quantization strategy to all features by assigning a number of bins that takes the square root of the number of data points in the sample (known as a square-root rule of thumbs).

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The selection of the feature set is guided by the following considerations. First, we want our set to include well-known, fast, and effective descriptors. We thus extract MPEG7 visual and motion standard descriptors (dominant color, color layout, scalable color, and others), which are detailed in [29]–[31]. With the same aim, for the audio dimension we include well-studied descriptive features, such as MFCC, subband distribution, and beat histogram, only to cite a few. These have been extensively described and tested in a number of publications, among which [32] and [33] are the most influential.

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Second, by scanning recent publications in content-based multimedia affective analysis we select the most promising descriptors, as well as those optimized across several publications (e.g., color energy and lighting key) such as [12] and [34]. From an architectural point of view, since we are aware that a more precise description of the connotative

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A. Scene Rating by Users

In the work in [4], we considered a set of 25 “great movie scenes” [26] belonging to popular films from 1958 to 2009 and we asked 240 users to rate each scene on the three connotative dimensions. Following Osgood’s evidences [27], rates $Y \in [1, 2, 3, 4, 5]$ were assigned on bipolar Likert scales based on the semantic opposites: warm or cold, dynamic or slow, and energetic or minimal. After rating, the position of a scene m_i in the connotative space is described by the histograms of rates on the three axes (H_i^N, H_i^T, H_i^E). In this paper, we compute interscene distances between couples (m_i, m_j) by using the Earth mover’s distance (EMD) [28] on the rate histograms of each axis (N, T, E) as follows:

$$\Delta_{i,j}^x = \text{EMD}(H_i^x, H_j^x) \quad x \in \{N, T, E\} \quad (1)$$

which are then combined to obtain the matrix of connotative distances between scenes as $\Delta^C = f(\Delta^N, \Delta^T, \Delta^E)$ (where function f in [4] is set so as to perform a linear combination of the arguments with equal weights on the three dimensions). In the following, we will refer to these scenes positioned by users’ rates as landmarks or training scenes.

B. Feature Extraction

From movie scenes, we extract features dealing with different aspects of professional content: visual dimension, both color and motion, audio, and film grammar. Since each feature F_i is extracted at its own time scale (frame, shot, and so on), values over a scene m_i are collected in a feature histogram $H_i^{F_i}$ to globally capture its intrinsic variability. For each feature, matrices of interscene distances Δ^{F_i} are computed as distances between feature histograms.

C. Feature Selection

To single out those features F_i^* that are the most related to users’ connotative rates, we adopt a feature selection criterion based on mutual information.

D. Regression

A support vector regression (SVR) approach builds a model to relate connotative distances based on users’ rates Δ^C to a function of interscene distances based on selected features $\Delta^{F_i^*}$.

373 dimensions could be obtained by enlarging the feature set,
374 the proposed system is scalable and open to the insertion of
375 additional features. The considered features are detailed in
376 the following paragraphs.

377 A. Visual Features

378 The visual dimension is perhaps one of the most important
379 ways of communication, which is exploited at its fullest by
380 directors while shaping a film product to convey a specific
381 message. Thus, in our attempt to capture the emotional identity
382 of a movie scene we consider the visual sphere and extract
383 color and motion descriptors, as presented in the following.

384 We consider MPEG7 color features that proved to be
385 effective in retrieval applications based on visual similarity:
386 dominant color, color layout, scalable color, and color structure
387 [30]. We also extract a codebook constituted by a set of
388 representative colors for a frame, obtained by using a vector
389 quantization approach in the YUV color space [35]. Beyond
390 standard descriptors we employ other visual features believed
391 to have a strong impact on the emotional identity of media
392 content [12]: color energy, lighting key, and saturation.

393 Color energy is related to the perceptual strength of the color
394 and depends on saturation, brightness, and area occupied by
395 different colors in an image. It also depends on the hue, as
396 in whether it contains more red (energetic) or blue (relaxing)
397 components and the degree of contrast between colors. The
398 result is a scalar indicating for each frame its perceived color
399 energy. For more details, please refer to [12].

400 Lighting conditions play a key role in scene definition.
401 To capture them we use two descriptors, proposed in [12],
402 referred to as lighting keys. They are related to two major
403 aesthetic lighting techniques: *chiaroscuro*, characterized by
404 high contrast between light and shadow areas, and *flat lighting*,
405 which de-emphasizes the light or dark contrast. Differences
406 between the two illumination techniques lie in the general light
407 intensity and the proportion of shadow area. Thus, for each
408 frame the first descriptor captures the median of the pixels'
409 brightness, while the second, accounting for the proportion of
410 shadow area, uses the proportion of pixels whose lightness
411 falls below the level for which a highly textured surface no
412 longer appears as such [12].

413 Previous work on affective response to colors proved that
414 saturation and difference in colors are crucial for mood
415 elicitation in subjects [36]. Thus, in addition to the already
416 mentioned features, we adopt two descriptors that account for
417 the average saturation of pixels, as well as their variance.

418 Finally, motion dynamics are often employed by directors
419 to stress the emotional identity of a scene. To transmit a
420 sensation of speed and dynamism or a feeling of calm and
421 tranquillity, directors often rely on shot pace and type, camera
422 and object motion. The motionDS descriptors introduced in
423 [31] capture the intuitive notion of intensity of action; in
424 particular, we measure the average of motion vector modules
425 and their standard deviation on consecutive frames.

426 B. Audio Features

427 Ambient sound, voices, and music of the soundtrack are
428 forms of expression which play central roles in shaping scene

affection and in the process of emotional involvement of the
audience [37]. As suggested by a relevant work on audio
analysis [32], we decide to describe audio signals in terms
of *intensity* (i.e., the energy of the sound, expressed by the
amplitude of the associated waveform), *timbre* (related to
the spectral shape of the sound and can be seen as the set
of qualities that allows us to distinguish two sounds from
different instruments), and *rhythm* (related to the repeating
sequence of stressed and unstressed beats and divided into
measures organized by time signature and tempo indications).
In the same work, as well as in other publications (such as
[33] and [38]), authors demonstrate that such a description
provides high performance for retrieval and classification of
audio signals in general, and especially for music.

The choice of privileging features mainly used in musical
audio analysis is due to the particular use of audio in movies:
scenes that are somehow central to narration are usually
stressed due to a particular choice of the soundtrack, e.g.,
gentle and pleasant music for a romantic moment, loud and
aggressive for an action sequence, silences and reprises in a
dialogue. In this perspective, audio energy can be seen as a
simple but effective clue. In this paper, we consider the energy
of an audio signal as the sum of the squared waveform values
over 20 ms frames, with 5 ms overlap, as suggested in [32].

Considered timbral features are low-energy ratio and zero-
crossing rate in the time domain; spectral rolloff, spectral
centroid, spectral flux, MFCC, and subband distribution in the
frequency domain. As in [32], except when differently stated,
timbral features are initially computed on overlapping frames
of 23 ms (analysis windows), so that frequency characteristics
of the magnitude spectrum are relatively stable. Actual features
are then obtained as average and standard deviation of analysis
windows over 1 s, since the sensation of sound "texture" arises
following some short-time spectrum pattern in time.

The low-energy ratio is defined as the percentage of analysis
windows that have less energy than average within the 1 s
window. As an example, vocal music with silences has a high
low-energy value, while continuous strings are at a low low-
energy value. The zero-crossing rate measures how many times
the waveform crosses the zero axis: a periodic and harmonic
sound shows a low crossing rate, while a noisy sound is
characterized by a high value of this descriptor.

A spectral centroid represents the magnitude spectrum's
center of mass of the signal and is interpreted as an index
of sound brightness. A limpid sound is usually characterized
by a high value of the center of mass, while a dark sound
by a low one. Spectral rolloff represents the frequency below
which 90% of the energy is concentrated and describes the
smoothness of a sound, i.e., the presence of high-frequency
harmonics in addition to fundamental tones. Spectral flux, in-
stead, characterizes variations of the frequency spectrum over
time. MFCC are perceptually based spectral descriptors widely
used for speech and audio classification [32] and are obtained
by a linear cosine transform of a log power spectrum on a
nonlinear perceptual frequency scale. The last timbral feature
is subband distribution, computed as in [33] on overlapping
windows of 3 s by decomposing in four subbands using the
Daubechies wavelets [39]. Extracted wavelet coefficients from



Fig. 4. Two frames from *A Beautiful Mind*. The left frame evokes a warm sensation, and the other a cold feeling.

each subband provide a compact representation of the energy distribution of the signal in time and frequency.

As for the rhythmic sphere, by using a beat detection algorithm as in [32], which works on chunks of 3 s, 50% overlapping, we derive the beat histogram and its cumulative value as a measure of the rhythmic strength of the audio track.

C. Film Grammar Features

When watching movies, the feeling is that some film directors have sharply different styles that are easily recognizable. These individual styles can be identified not only in the content, but also from the formal aspects of the films, known as film grammar [40], which encompasses the set of rules followed by a director to convey a certain message.

As proposed in [41], the obvious approach to searching for individual characteristics in the formal side of a director's grammar is to consider those variables that are most directly under the director's control. Among these, shot length (meant as duration), shot type in terms of camera distance to subjects (closeups, medium shots, or long shots), camera movement (such as panning, tilting, or zooming), shot transitions (cuts, fades, dissolves, wipes), and lighting conditions are grammar aspects that can be automatically investigated. In this paper, we consider as a first set of film grammar features, meaning that they are directly under the director's control, the shot length, the color of the illumination source, and the pattern of shot type.

Shot length greatly affects how a scene is perceived by the audience. Longer durations connote a scene as more relaxed and slower paced, whereas shorter shots give the impression of a faster paced scene [42]. Thus, we extract the average shot length as an effective scene descriptor.

The second feature is related to the spectral composition of the light source, which is often exploited by directors to give a connotative signature to movies. Light used in the shooting process, called illuminant, influences the appearance of every element in the scene: objects do not have their own colors, which are instead due to the interaction with the incident electromagnetic radiation. In Fig. 4, the frame on the left shows a scene with a yellow polarized illuminant which evokes a pleasant sensation, while the one on the right suggests a colder feeling because of the grayish illuminant. Here, for each frame we estimate the illuminant color by improving a white patch algorithm [43] with the procedure we propose in [44].

The third descriptor accounts for the change of employed shot types. Varying camera distance is a common directing rule used to subtly adjust the relative emphasis between the filmed subject and the surrounding scene [13]. This affects the

emotional involvement of the audience [40] and the process of identification of viewers with the movie characters. There are, in fact, evident correspondences between the film-maker's choice of shot type and the proxemic patterns [45], i.e., the subjective dimensions that surround each of us and the physical distances one keeps from other people in social life. Although the gradation of distances is infinite, in practical cases the categories of definable shot types can be re-conducted to three fundamental ones: long shots, medium shots, and closeups (see [40] for a complete taxonomy). First, for each scene we estimate the type of employed shots by the algorithm presented in [46]. Then, we define the shot type transition rate as the number of type changes across consecutive shots in a scene, normalized to the total number of shots. As shown in [47], this rate is in fact part of the complex mechanism responsible for triggering audience's emotional involvement, with strong evidences especially on the arousal dimension.

V. FEATURE SELECTION

A feature selection method is applied to disclose the relationships between scene coordinates in the connotative space assigned by users and the related audiovisual features. This step aims at unveiling which are the audiovisual descriptors that mostly affect user's perception of connotative properties to be employed in the regressive models adopted in Section VI.

Feature selection algorithms are very popular in several disciplines [48], such as gene expression, array analysis, combinatorial chemistry, and multimedia analysis. Given a number of descriptors, they aim at discriminating between those relevant for a certain goal from those that are not, allowing the learning step which usually follows to work with a compact set of significant features. The main advantages are reduction of the number of features to be processed, exclusion of redundant or inefficient ones, and a better understanding of the problem.

The definition of the right selection algorithm for a specific problem depends on several aspects. One possible choice is to integrate the feature selection within the subsequent regression algorithm (e.g., to use a support vector approach for feature selection embedded in an SVR), as suggested, for example, in [49]. However, instead of applying such a procedure, called *wrapping*, we prefer to apply a filtering method, i.e., to keep separated selection and prediction. Filtering methods, apart from being in general computationally less expensive than wrappers [50], usually provide an easier understanding of the selection problem. In addition to this, they are independent of the ensuing learning method, thus allowing the study of the effectiveness of the features with different regression approaches, as we perform in Section VI.

For our specific goal of discovering audiovisual features relevant to connotation, a potential issue is redundancy; it is, in fact, likely that if a particular descriptor is relevant, other descriptors that are correlated to the first one result relevant too. For this reason, we employ an information theory-based filter that selects the most relevant features in terms of mutual information with user votes, while avoiding redundant ones: the minimum-redundancy maximum-relevance (mRMR) scheme introduced in [51].

590 Given the set of L features $\{F_l\}_{l=1,\dots,L}$ and the user votes Y
 591 on each connotative axis, both interpreted as random variables,
 592 consider *relevance* (V) and *redundancy* (W) defined as

$$V = \sum_{F_l \in S} \frac{I(F_l, Y)}{|S|} \quad W = \sum_{(F_l, F_j) \in S \times S} \frac{I(F_l, F_j)}{|S|^2} \quad (2)$$

593 where I indicates the mutual information and S is the
 594 set of selected descriptors. The goal is to select a sub-
 595 set of M features ($M = |S|$, $M < L$) as informative as pos-
 596 sible with respect to users' votes ($\max(V)$) and, at the
 597 same time, as uncorrelated as possible among themselves
 598 ($\min(W)$). A possible criterion (exposed in [51]) to jointly
 599 optimize both conditions treating them as equally important
 600 is to maximize the difference between quantities in (2):
 601 $\max(V - W)$.

602 To solve this optimization problem, a heuristic called mutual
 603 information difference criterion (MID) is used, as in [52].
 604 According to it, the first selected feature F_f is the most
 605 relevant ($I(F_f, Y) \geq I(F_l, Y)$, $l = 1, \dots, L$), while other fea-
 606 tures are added in an incremental way; for each candidate
 607 feature F_l not yet in S , the quantities in (2) are recomputed as
 608 follows:

$$\widehat{V}_l = I(F_l, Y) \quad \widehat{W}_l = \sum_{F_j \in S} \frac{I(F_l, F_j)}{|S|} \quad (3)$$

609 and the newly selected feature is the one so that

$$\arg \max_{F_l \notin S} (\widehat{V}_l - \widehat{W}_l). \quad (4)$$

610 A. Sample Probabilities on Distances

611 To compute mutual information $I(\cdot, \cdot)$ it is necessary to
 612 sample probabilities of features and votes. However, when
 613 dealing with multidimensional feature histograms H^{F_l} , the
 614 direct application of such a procedure is impractical. This is
 615 due to the number of scenes that would be required if we
 616 wanted to compute reliable statistics, both marginal and joint,
 617 on all possible combinations of feature values and users' votes.

618 To overcome this issue, for the selection and regression steps
 619 we do not take into account actual histograms, but distances
 620 between them. Therefore, we do not employ the absolute
 621 position of scenes, but the knowledge of how they are placed
 622 with respect to all others, both in connotative and in feature
 623 spaces. Such a scheme naturally fits our aim, which is, in fact,
 624 to recommend movie scenes according to their proximity in
 625 the connotative space. Approaches based on distances between
 626 items are also closer to the human mechanism of perceiving
 627 emotions, which works in a comparative way rather than using
 628 an absolute positioning, as shown in [53] for music items.

629 For our aims we then consider interscene distances based
 630 on users' rates Δ^x as expressed in (1), and distances based on
 631 feature histograms Δ^{F_l} . In the specific, for each descriptor F_l ,
 632 the element of Δ^{F_l} in position i, j is given by

$$\Delta_{i,j}^{F_l} = \text{EMD} \left(H_i^{F_l}, H_j^{F_l} \right) \quad i, j = 1, \dots, 25. \quad (5)$$

TABLE II
 FEATURE RANKING AND RELEVANCE \widehat{V} ACCORDING TO THE MRMR
 MID SCHEME (SELECTED ONES ARE IN BOLD)

NATUR.	\widehat{V}	TEMP.	\widehat{V}	ENERG.	\widehat{V}
Col.layout	0.22	Rhyt.str.	0.27	Sound en.	0.18
Spec.roll.[d]	0.14	Shot ty.t.r	0.15	Shot len.	0.09
Light.key II	0.11	Mot.DS[d]	0.25	Spec.ce.[d]	0.06
Illuminant	0.19	Sound en.	0.10	Sub.dist.[a]	0.06
Spec.ce.[d]	0.07	Spec.ce.[d]	0.18	Satur.[d]	0.07
Sound en.	0.06	Sub.dist.[a]	0.03	Col.layout	0.07
Col.codeb.	0.21	Shot len.	0.07	Spec.roll.[d]	0.05
Zero cr.r.[d]	0.12	MFCC [d]	0.08	Rhyt.str.	0.12
Shot ty.t.r.	0.07	Scal.col.	0.09	Spec.flux[d]	0.04
Col.en.	0.08	Satur.[d]	0.04	Beat hist.	0.05
Col.sat.[a]	0.06	Spec.cen.[a]	0.17	Shot ty.t.r.	0.05
Sub.dist.[a]	0.05	Low en.r.	0.03	Col.struc.	0.04
Mot.DS[a]	0.07	Light.key I	0.05	Col.en.	0.04
Shot len.	0.04	Spec.flux[a]	0.04	MFCC[d]	0.06
MFCC[a]	0.06	Mot.DS[a]	0.13	Spec.roll.[a]	0.04
Col.struc.	0.08	Col.en.	0.04	Illuminant	0.04
Scal.col.	0.16	Zero cr.r.[a]	0.04	Mot.DS[d]	0.06
Satur.[d]	0.03	Zero cr.r.[d]	0.03	Low en.r.	0.03
Low en.r.	0.04	Ligh.key II	0.03	Sub.dist.[d]	0.06
Dom.col.	0.18	Illuminant	0.03	Spec.flux[a]	0.05
Beat hist.	0.04	Spec.flux[a]	0.04	Light.key II	0.04
Spec.flux[d]	0.03	Beat hist.	0.03	Zero cr.r.[a]	0.03
Zero cr.r.[a]	0.12	MFCC[a]	0.05	Light.key I	0.05
Rhyt.str.	0.05	Spec.roll.[d]	0.02	Satur.[a]	0.04
MFCC[d]	0.06	Sub.dist.[d]	0.09	Scal.col.	0.07
Sub.dist.[d]	0.05	Col.layout	0.04	Mot.DS[a]	0.04
Light.key I	0.06	Spec.roll.[a]	0.02	MFCC[a]	0.04
Spec.flux[a]	0.03	Col.struc.	0.03	Zero cr.r.[d]	0.03
Spec.roll.[a]	0.03	Satur.[a]	0.02	Col.codeb.	0.07
Spec.cen.[a]	0.05	Col.codeb.	0.06	Spec.cen.[a]	0.03
Mot.DS[d]	0.04	Dom.col.	0.05	Dom.col.	0.03

Those computed in average and std dev are indicated with [a] and [d], respectively.

633 After normalizing and quantizing EMD distances¹ on five
 634 levels as for distances in the connotative space, we compute
 635 the mutual information between distances based on feature
 636 histograms and connotative distances based on users' rates on
 637 a proper number of samples. The MID criterion is then reform-
 638 ulated as follows: for each connotative axis $x \in \{N, T, E\}$,
 639 the first selected feature F_f is the one so that

$$I(\Delta^{F_f}, \Delta^x) \geq I(\Delta^{F_l}, \Delta^x) \quad l = 1, \dots, L \quad (6)$$

640 while the following features are added as in (4) where:

$$\widehat{V}_l = I(\Delta^{F_l}, \Delta^x) \quad \widehat{W}_l = \sum_{F_j \in S_x} \frac{I(\Delta^{F_l}, \Delta^{F_j})}{|S_x|}. \quad (7)$$

641 This way, according to the MID criterion, we rank features
 642 for each connotative axis, as shown in Table II.

¹It is worth noticing that the EMD computation is based on the definition of a ground distance, i.e., the distance between two samples of the considered feature. In our work, we use for each feature the *ad hoc* ground distance, as found in the literature: distances as proposed for MPEG7 descriptors in [30], L^2 on RGB components for the illuminant color, and so on, while for users' votes expressed on Likert scales we adopt L^1 distance.

643 B. Relevant Feature Sets

644 The next crucial aspect is the number of features to select
 645 for the regression step; keeping too many descriptors would
 646 increase the computational cost of the extraction process,
 647 while considering too few descriptors would potentially lead
 648 to a poor regression model. Following these considerations
 649 we keep, for each connotative axis, only those features that
 650 are able to increase the level of mutual information between
 651 features and connotative votes above a minimum contribution.

652 In terms of MID criterion, considering a set S_x of already
 653 selected features for the x -axis, the next feature in the ranking
 654 list F_l is selected if its contribution $\widehat{V}_l - \widehat{W}_l$ [computed as in
 655 (7)] satisfies the condition

$$\widehat{V}_l - \widehat{W}_l \geq r \cdot I(\Delta^{F_l}, \Delta^x) \quad (8)$$

656 where $r \in [0, 1]$ and $I(\Delta^{F_l}, \Delta^x)$ is the mutual information of
 657 the first ranked feature for that axis, i.e., the best descriptive
 658 one with respect to user's votes. To find the optimal value for
 659 r , we scan the range of values between 0 and 1 and measure
 660 recommendation performance on ranked lists against a ground
 661 truth (as described in Section VII-A). In general, we notice that
 662 recommendation performance improves when the number of
 663 selected features increases, i.e., when r diminishes. However,
 664 if r becomes too low, thus including even not so significant
 665 or noisy features in terms of mutual information with users'
 666 votes, the effectiveness of the system stops increasing. There-
 667 fore, during tests in Section VII-A, we determine that the
 668 optimal value, in the sense that it maximizes recommendation
 669 performance and minimizes complexity in terms of number of
 670 descriptors to be extracted, corresponds to $r = 0.15$. By setting
 671 this value, we select four features for the natural dimension,
 672 three for the temporal one, and two for the energetic one (in
 673 bold in Table II). As a reinforcement for the operated choice
 674 on r , we notice that selected features make intuitive sense for
 675 all axes.

676 As seen in [4], the natural dimension is related to warm
 677 or cold affections, and it is voted by users as the scene
 678 atmosphere. As expected, selected features for this axis are
 679 intuitively involved in the characterization of a scene's atmo-
 680 sphere; they, in fact, describe the color composition (color
 681 layout), the variations in smoothness and pleasantness of the
 682 sound (spectral rolloff standard deviation) and the lighting
 683 conditions in terms of both illumination (illuminant color)
 684 and proportion of the shadow area in a frame (one of the
 685 lighting key descriptors which is dramatically stressed in the
 686 chiaroscuro technique).

687 The temporal axis has been rated by users in terms of
 688 high pace versus slowness. The algorithm returns for this axis
 689 the rhythmic strength of the audio signal, which is an index
 690 related to the rhythm and the speed sensation evoked by a
 691 sound, the pace variation of the employed shot types (shot
 692 type transition rate), and the variability of the motion activity
 693 (standard deviation on motion vector modules).

694 User votes on the energetic dimension distinguish items with
 695 high affective impact from minimal ones. Selected features
 696 are again commonsensical and coherent: the first describes
 697 the sound energy, while the second one is the shot length; for

TABLE III
 APPROXIMATION ERROR ON SCENE DISTANCES BASED ON USERS'
 VOTES IN TERMS OF RMSE, OBTAINED USING THE
 REPORTED REGRESSION METHODS

Regression method	RMSE
Polynomial regression	0.281
Neural network	0.248
SVR	0.188

Distances are normalized in the range [0, 1].

example, short shots usually employed by directors in action
 scenes are generally perceived as very energetic.

VI. REGRESSION

Once features relevant to connotative votes on each axis are
 picked, we aim at estimating connotative distances Δ^x based
 on rates by a function of distances based on selected features

$$\Delta^x \approx \widehat{\Delta}^x = g_x(\{\Delta^{F_l}\}_{F_l \in S_x}). \quad (9)$$

To define functions g_x that best link the denotative level with
 the connotative dimensions, we set up a modelling framework
 using selected features as inputs and connotative votes as
 desired outputs (not in absolute terms but as distances).

In order to compare different regressive procedures for
 approximating the desired output starting from the inputs, we
 test in particular polynomial combination, neural networks
 (feed-forward neural network trained by a back-propagation
 algorithm), and SVR models [54] with standard RBF kernel.
 Modelling functions g_x are then obtained for dimensions
 $x \in \{N, T, E\}$ by adopting SVR models that are the ones that
 return the lowest root mean squared error on scene distances
 based on users' votes, as reported in Table III.

This modeling step provides a way to translate video
 properties into intermediate semantic connotative concepts,
 which are mostly agreeable among individuals. As a result,
 the approximated matrix of connotative distances is found as
 follows:

$$\widehat{\Delta}^C = f(\widehat{\Delta}^N, \widehat{\Delta}^T, \widehat{\Delta}^E) \quad (10)$$

where function f is set as in (1).

VII. EXPERIMENTS ON SCENE RECOMMENDATION

The idea of the affective recommendation scenario here pro-
 posed is that once a user expresses an implicit emotional wish
 by selecting a query item (e.g., by choosing a happy scene
 in his or her opinion), the recommendation algorithm should
 return a list of candidate movie scenes that are emotionally
 close to the given query for that user. This kind of query-by-
 example approach has its roots in information filtering, and
 goes under the name of content-based recommendation [55]
 (as opposed to other methods, e.g., collaborative filtering [15]).

Recommendation results are returned as top-k lists, a con-
 cept ubiquitous in the field of information retrieval (e.g., the
 list of k items in the first page of results by a search engine).
 They are a valid mechanism for propagating emotional tags
 from the already watched content to close items, thus enabling

738 better filtering of relevant items from the nonrelevant ones as
 739 in [17]. The following experiments aim to measure the ability
 740 of the connotative space in proposing content relevant to user's
 741 emotional preferences.

742 A. Ranking Lists Against a Ground Truth

743 To evaluate how good distances based on selected features
 744 $\hat{\Delta}^C$ approximate scene distances computed on users' rates
 745 Δ^C , we compare the abilities of the two distance matrices
 746 in ranking lists of movie scenes with respect to ground-truth
 747 lists built by single users.

748 This first experiment uses the data gathered by the 240
 749 users on the 25 movie scenes in [4]. The collective users'
 750 emotional annotations are expressed in the form of emotional
 751 distances Δ^W between scenes, while the ground-truth lists per
 752 each single user u_k are built by the emotional distances $D_{u_k}^W$
 753 between scenes expressed by that specific user. By observing
 754 the emotion wheel [4] in Fig. 6 we recall that the distance
 755 between two emotions e_i and e_j is the number of steps required
 756 to reach emotion e_j from emotion e_i , as stated by Russell in
 757 [56] and recently adopted by Irie *et al.* in [14] as well as in
 758 our test in [4]. As Russell observes, "a score of 1 (is assigned)
 759 to the distance between adjacent terms," whereas "a distance
 760 4 is assigned between terms placed opposite on the circle,"
 761 no matter whether computed clockwise or counterclockwise.
 762 Please observe that $D_{u_k}^W$ is not a distance between distributions
 763 of votes (as Δ^W is since it aggregates all users' votes), but is
 764 a distance between scene emotions assigned by a single user.

765 In the proposed test, given a user and a *query* item, all
 766 movie scenes are first matched according to how emotionally
 767 similar they are to the query item, according to single user's
 768 emotional annotations (i.e., the ground truth in $D_{u_k}^W$). Second,
 769 this list of scenes is re-ranked based on distances expressed
 770 in Δ^C (i.e., ranking by connotative rates), which expresses
 771 the ability of the connotative space in matching the affective
 772 preferences of single users. In [4], we have already shown
 773 that to recommend movie scenes, connotation (Δ^C) works
 774 better than using aggregated emotions by all users (Δ^W)
 775 to approximate the ground-truth ranking obtained using $D_{u_k}^W$.
 776 Here, we also consider the case when ranking is performed
 777 by using the learned models, i.e., how good is the ranking
 778 obtained by using the approximated distances $\hat{\Delta}^C$ provided
 779 by the SVR models (i.e., ranking by connotative properties
 780 predicted by audiovisual features).

781 Ranking quality is measured by the Kendall's tau metric
 782 K [57], which is equal to the number of exchanges needed
 783 in a bubble sort to convert one ranked list to the other one,
 784 normalized in the interval $[0, 1]$.

785 In this process, we apply a five-fold cross validation ap-
 786 proach. At each round 20 scenes are used to build the models,
 787 and the metric K is measured on the five remainders. Folds
 788 are manually arranged using stratification [58], thus ensuring
 789 that scenes are balanced as much as possible with respect to
 790 the connotative votes assigned by users.

791 As a result, considering as ground-truth lists those ranked
 792 by single users' emotional annotations $D_{u_k}^W$ (for which $K = 0$),
 793 the average error performed by using Δ^C to rank scenes is
 794 $K_{\Delta^C} = 0.425$, while the average error performed by using

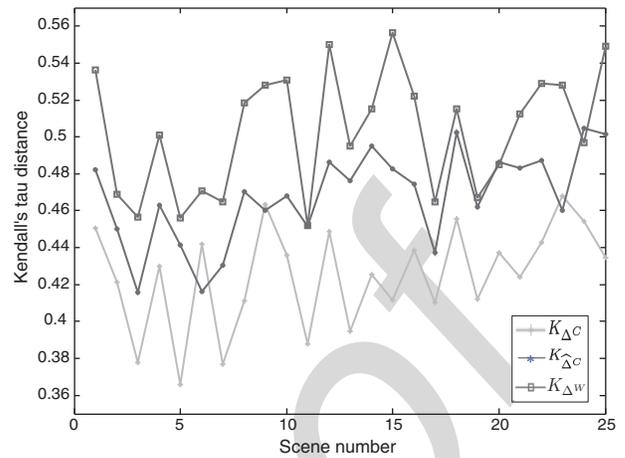


Fig. 5. Kendall's tau metric measuring the quality of list ranking by using connotative distances based on votes (K_{Δ^C}) and by distances approximated with the learning models ($K_{\hat{\Delta}^C}$) (values gathered on a scene basis and averaged on five-folded models). Since the ground-truth lists are at $K = 0$, both Δ^C and $\hat{\Delta}^C$ perform better than ranking lists by using emotional annotations aggregated by all users (Δ^W).

795 $\hat{\Delta}^C$ to rank scenes is just slightly above, $K_{\hat{\Delta}^C} = 0.467$,
 796 however, still inferior than the error performed when using
 797 Δ^W ($K_{\Delta^W} = 0.502$). Inspecting results in Fig. 5 (which shows
 798 Kendall's tau scores for each of the 25 scenes, as an average
 799 result on the five-folded evaluation) in a comparative way, we
 800 can conclude that even if the regression undeniably introduces
 801 an error, when the goal is not to replicate exact connotative
 802 distances but to obtain a similar ranking, the average ability
 803 of the system does not significantly degrade when using $\hat{\Delta}^C$
 804 instead of Δ^C . More importantly, returned lists using $\hat{\Delta}^C$ better
 805 match the ground-truth lists per each single user than using
 806 the aggregated annotations by other users Δ^W , meaning that
 807 even connotative properties predicted by audiovisual features
 808 are more intersubjectively agreed among people than collective
 809 emotional annotations.

810 B. Scene Recommendation: User Test

811 The first test that employed a ground truth is here expanded
 812 in a larger application scenario for recommending novel movie
 813 scenes to users. For this second user test, which is performed
 814 online with support of English language, 38 users were re-
 815 cruited. When performing the test, they were not aware of the
 816 final aims of the research.

817 Regarding the scene database, we would like to remark that
 818 while ground-truth databases for events and objects analysis
 819 in videos are available and relatively easy to build (they can
 820 be annotated by one single person and be objectively valid
 821 for almost everyone else), large ground-truth video databases
 822 where each video scene is emotionally (and subjectively)
 823 annotated by a large number of users do not yet exist. In our
 824 experiment, in addition to the 25 landmarks, 50 new scenes
 825 not previously involved in modelling are adopted as candidates
 826 for recommendation for evaluating users' satisfaction with the
 827 system, for a total number of 75 scenes. The complete list
 828 of employed scenes provided with title, duration, year, IMDb
 829 film rank, and (for the new 50 scenes) the available online
 830 links for inspection, can be found in [59].



Fig. 6. User test interface: example of a scene to be annotated with an emotional tag chosen among those on the emotion wheel [4] (happiness, excitement, tension, distress, sadness, boredom, sleepiness, relaxation).

831 While the first test could be evaluated in terms of Kendall's
 832 tau metric against relatively short ground-truth lists built by
 833 each user, for a database of 75 scenes it is not possible to
 834 produce ground-truth lists, since it is unfeasible for each user
 835 to rate all new scenes in an limited time without losing focus
 836 and attention.

837 For this reason, each user is asked to query the recommenda-
 838 tion system only two times, and rate only three top and
 839 three bottom results per each query, for a total number of 14
 840 voted scenes per user (12 rates on scenes plus 2 annotated
 841 queries). With the described procedure, 38 users provide
 842 more than 500 votes, which allows for gathering reliable
 843 statistics on the 75 scenes. To the best of our knowledge,
 844 no other work on content affective analysis so far recruited
 845 such a large number of users on video recommendation tests
 846 (almost 300 users, considering both tests).

847 To start the test, each user chooses as query items two
 848 landmark scenes and tags each with one emotional label
 849 chosen among the eight available on the emotion wheel, as
 850 shown in Fig. 6. The system returns, for each query, a list of
 851 six movie scenes that contains, in a random order, the top-3
 852 close scenes in the connotative space and the three most distant
 853 ones from the query (among the 75 total scenes). To verify
 854 the ability of the connotative space in recommending similar
 855 affective items, we ask users to annotate each proposed scene
 856 with one emotional tag, as shown in the interface of Fig. 6.

857 Since each user, given a query, is required to watch only
 858 a limited number of scenes (the top-3 close and the top-3 far
 859 items), recommendation results can be evaluated in terms of
 860 precision@k: the number of results which are judged to be *rel-*
 861 *evant* by the user among the first $k = 3$ recommended results.

862 However, we try to do more than that; instead of stating
 863 whether a result is just relevant or not-relevant, the performed
 864 test allows us to state to what extent an item is relevant by
 865 measuring the scene emotional distances expressed by the user
 866 from the query ($d = 0$ "scene with same emotion," $d = 1$
 867 "scene with similar emotion," ..., $d = 4$ "scene with opposite
 868 emotion"), which is also closer to the human mechanism of
 869 perceiving emotions, which works in a comparative way rather
 870 than using absolute terms.

871 In this sense, if we consider as relevant only those recom-
 872 mendations that are at null emotional distance ($d = 0$), then
 873 precision@3 is 0.3 for top-3 close items. However, considering
 874 as relevant also items that are emotionally similar ($d \leq 1$),
 875 precision@3 raises to a significant 0.68. All precision@3
 876 results are shown in Table IV for both top-3 close and top-3
 877 far scenes at different emotional distances.

TABLE IV

PRECISION@3 RESULTS FOR (LEFT) TOP-3 CLOSE AND (RIGHT) TOP-3 FAR SCENES AT DIFFERENT EMOTIONAL DISTANCES

top-3 close	precision@3	top-3 far	precision@3
$d=0$	0.30	$d=4$	0.22
$d \leq 1$	0.68	$d \geq 3$	0.59
$d \leq 2$	0.87	$d \geq 2$	0.82
$d \leq 3$	0.95	$d \geq 1$	0.97
$d \leq 4$	1.00	$d \geq 0$	1.00

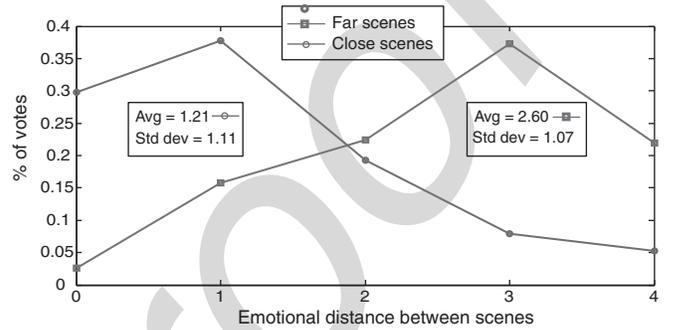


Fig. 7. Histogram (blue) of the emotional distances between the query and the top-3 close recommended items and histogram (red) of the emotional distances between the query scene and the top-3 far scenes. Distances are in the range [0, 4] (0: "same emotion as query" and 4: "opposite emotion").

878 Fig. 7 summarizes the obtained results by showing the
 879 histogram of emotional distances of the top-3 close scenes
 880 (blue) and the histogram of distances of the top-3 far scenes
 881 (red) from the query. They approximate the probability dis-
 882 tribution functions of perceived emotional distances between
 883 the query and the recommended items. Since they consider
 884 precision computed at different scales of relevance (i.e., at
 885 different emotional distances d), they can be considered as
 886 more informative than a single value of precision@k stating
 887 whether a result is just relevant or not.

C. Discussion

888 In [4], we have already shown that the connotative judge-
 889 ments are more effective than using people's affective re-
 890 sponses in recommending content able to target the emotional
 891 request of a single user.

892 In this paper, we push this result one step further. We, in
 893 fact, state that it is possible to automatically position a movie
 894 scene in the connotative space by analyzing its audiovisual
 895 and grammar features without asking users to express their
 896 perception of film connotative properties. By selecting au-
 897 diovisual descriptors relevant to connotation, we are able to
 898 map movie scenes in the connotative space, and to discover
 899 similar and dissimilar affective content by computing distances
 900 in this space. The first test in Section VII-A demonstrates that
 901 using audiovisual properties to derive connotative coordinates
 902 introduces a risible drop in performance if compared to
 903 connotative rating by users.

904 In the recommendation scenario, when the user wishes to
 905 get some content eliciting a particular emotion, the system
 906 automatically proposes content which in the connotative space
 907 is close to some items already tagged by the user with the
 908

desired emotion. In this final experiment, we checked users' satisfaction with recommendation results by computing the emotional distances between the emotions elicited by the query item and by the suggested scenes.

This way, we have closed the loop: at the beginning the user expresses an emotional wish; to target this, we use already tagged content that elicited in that specific user that emotional reaction. We then look for similar content in the connotative space, and finally ask the user which emotion he or she is inspired with to check the correctness of the emotional recommendation. The outcome of the experiment, as summarized in Table IV and Fig. 7, reveals the effectiveness of the connotative space in proposing content eliciting similar affective reactions.

Notice that content close in the connotative space can be very different in terms of denotative meaning; it happens, for example, that a fight in *Kill Bill II* is recommended on the base of the chariot chase in *Ben Hur*. Even if different in content, both scenes elicit a similar affective reaction in the same user, which is the basic idea of affective recommendation.

A few last considerations on scenes, database dimensions, and future work. Experiments performed in this paper use movie scenes as elementary units since, by definition, each scene in a movie depicts a self-contained high-level concept. We are aware that a recommender system of video scenes has little practical purpose. However, starting from understanding how the system behaves with elementary units of film items is a valid practical approach for future extensions to full movies. To the best of our knowledge, no experiments on affective recommendation on full movies have been attempted so far. Thus, our next research goal is to extend our approach to full movie recommendation.

Of course, working on full movies introduces severe scalability issues to our approach, which are worth discussing. In this paper, each scene is represented as a point in the connotative space. When using full movies instead, the idea is to consider a connotative cloud of scenes or, considering the time dimension, a connotative trajectory that interconnects subsequent scenes in the film.

Even if there is an undeniable technical difficulty in conducting experiments on larger scene databases, we are already tackling this scalability challenge, from both the system and the algorithm time complexity's standpoints. By exploiting the knowledge about the position of a few landmark scenes, it is indeed possible to assign other scenes with absolute positions instead of using distances between scenes. Thus, once a reliable set of landmark scenes is found, new scenes and movies can be added without much complexity, ensuring adequate scalability to the system.

The fact that the system is actually open to the insertion of new scenes and movies, so that users can get more and more recommended items as long as the database increases, is indeed an asset of the system. In fact, while now with 75 scenes it might happen that some scenes have no close neighbors in the connotative space (so that users might be not fully satisfied with the recommended items), the more the database grows, the higher the chances that proper emotional content is found.

VIII. CONCLUSION

In this paper, we proposed an affective framework where movie scenes are placed, compared, and recommended by extracting audiovisual and film grammar features. The learning model allowing to link physical features of videos to users' emotional preferences was driven by users' rates on connotative properties, defined as the set of shooting and editing conventions that helped in transmitting meaning to the audience. Connotation here provided an intermediate representation level that exploited the objectivity of audiovisual descriptors to match the emotional queries of single users. To demonstrate the validity of this approach, we conducted a first test of the model against a ground truth to verify the translation process of relevant audiovisual low-level descriptors into connotative properties. Then, a final user test verified the ability of the connotative framework to recommend items matching users' affective requests, thus positively answering to both initial research questions. Further studies on the extension of the current scene-based method to full movies are currently ongoing.

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