

Asymptotic behavior of a nonlinear hyperbolic heat equation with memory*

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Abstract. In this paper we investigate the asymptotic behavior, as time tends to infinity, of the solutions of an integro-differential equation describing the heat flow in a rigid heat conductor with memory. This model arises matching the energy balance, in presence of a nonlinear time-dependent heat source, with a linearized heat flux law of the Gurtin-Pipkin type. Existence and uniqueness of solutions for the corresponding semilinear system (subject to initial history and Dirichlet boundary conditions) is provided. Moreover, under proper assumptions on the heat flux memory kernel and the magnitude of nonlinearity, the existence of a uniform absorbing set is achieved.

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1 Introduction

We consider the following semilinear integro-differential equation in a bounded domain $\Omega \subset \mathbb{R}^3$:

$$\begin{aligned} u_t(x, t) - \int_0^\infty k(\sigma) \Delta u(x, t - \sigma) d\sigma + g(u(x, t)) &= f(x, t) && \text{in } \Omega \times \mathbb{R}^+ \\ u(x, t) &= 0 && x \in \partial\Omega \quad t \in \mathbb{R} \\ u(x, t) &= u_0(x, t) && x \in \Omega \quad t \leq 0 \end{aligned} \tag{1.1}$$

where k is a positive kernel decreasing to zero, whose properties will be specified later.

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Problem (1.1) models temperature evolution of a rigid, isotropic, homogeneous heat conductor with linear memory, which occupies a fixed domain $\Omega \subset \mathbb{R}^3$. Indeed, let $\vartheta : \Omega \times \mathbb{R}^+ \rightarrow \mathbb{R}$ be the *absolute temperature* of the conductor, $\vartheta_0 \in \mathbb{R}^+$ the *uniform equilibrium temperature* and

$$u(x, t) = \frac{\vartheta(x, t) - \vartheta_0}{\vartheta_0}$$

the *temperature variation field* relative to the equilibrium reference value. According to the well-established theory due to Gurtin and Pipkin [9], we consider only small variations of the absolute temperature and the temperature gradient from equilibrium, namely,

$$|u| \ll 1 \quad \text{and} \quad \frac{1}{\vartheta_0} |\nabla \vartheta| = |\nabla u| \ll 1$$

and we suppose that the *internal energy* $e : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ and the *heat flux vector* $\mathbf{q} : \Omega \times \mathbb{R} \rightarrow \mathbb{R}^3$ are described by the following linear constitutive equations:

$$\begin{aligned} e(x, t) &= e_0 + c_0 u(x, t) \\ \mathbf{q}(x, t) &= - \int_{-\infty}^t k(t-s) \nabla u(x, s) ds \end{aligned}$$

where the *heat flux memory kernel* $k : \mathbb{R}^+ \rightarrow \mathbb{R}$ is a sufficiently smooth, positive, summable function decreasing to zero at infinity. The positive constants e_0 and c_0 denote the *internal energy at equilibrium* and the *specific heat*, respectively. As usual, temperature evolution in a rigid heat conductor is governed by the *energy balance* equation. Here, assuming that the heat supply consists of a nonlinear temperature-dependent term, $-g(u)$ (accounting for certain types of laser induced radiative phenomena [10]), and a time-varying source f , the energy equation takes the form

$$e_t(x, t) + \nabla \cdot \mathbf{q}(x, t) = f(x, t) - g(u(x, t)).$$

Taking $c_0 = 1$ and assuming the isothermal condition $\vartheta = \vartheta_0$ at the boundary $\partial\Omega$, we obtain (1.1), where u_0 represents the prescribed *initial past history* of u , which is assumed to vanish on $\partial\Omega$, as well as u .

Finally, we mention that (1.1) is suitable to describe other physical phenomena: for instance, the motion of a viscoelastic fluid in a tube, and the Olmstead model for reaction-diffusion processes in media with memory (see [13]).

At first glance, the hyperbolic nature of problem (1.1) is not apparent. Indeed, calling

$$\beta = \int_0^\infty k(\sigma) d\sigma > 0$$

we may rewrite our equation as

$$u_t - \beta \Delta u + \int_0^\infty k(\sigma) \Delta [u(t) - u(t - \sigma)] d\sigma + g(u) = f. \quad (1.2)$$

So, if we neglect the hereditary term, we obtain a semilinear parabolic equation whose longtime behavior has been studied by many authors (see, for instance, [1, 16]).

On the other hand, by differentiation with respect to time, equation (1.1) can be transformed into the second order integro-differential equation

$$u_{tt} - k(0) \Delta u - \int_0^\infty k'(\sigma) \Delta u(t - \sigma) d\sigma + g'(u)u_t = f_t \tag{1.3}$$

which reduces to a hyperbolic equation with nonlinear damping when the memory term is neglected and $k(0)$ is assumed to be positive. As a particular case, when the heat flux memory kernel takes the form

$$k(s) = k_0 \exp \left[-\frac{s}{\sigma_0} \right]$$

(1.3) yields the following (hyperbolic) differential equation

$$\sigma_0 u_{tt} + [1 + \sigma_0 g'(u)] u_t - \sigma_0 k_0 \Delta u + g(u) = f + \sigma_0 f_t. \tag{1.4}$$

The hyperbolicity of (1.1) when $k(0) > 0$ is properly expressed by the fact that the energy of a perturbation, initially given in a compact subset of Ω , propagates with a *finite speed* $c \geq \sqrt{k(0)}$ (cf. [3]).

In the sequel we shall require the nonlinear term g in (1.1) to comply some dissipativeness condition. Nevertheless an antidissipative behavior for small values of its argument will be allowed. For instance, if g is a cubic-like function of the form $g(u) = u^3 - \gamma u$ and the product $\gamma\sigma_0$ is large enough, then the coefficient of u_t in (1.4) is negative for $|u|$ small. When this is the case, it is not necessarily true that bounded solutions converge to equilibria, and the dynamical behavior of the system is expected to be more complicated.

Concerning the heat flux memory kernel, we assume that there exists $\alpha > 0$ such that, defining the kernel

$$\mu(s) = -k'(s) - \alpha k(s)$$

the following hold:

- (h1) $\mu \in C^1(\mathbb{R}^+) \cap L^1(\mathbb{R}^+)$
- (h2) $\mu(s) \geq 0 \quad \forall s \in \mathbb{R}^+$
- (h3) $\mu'(s) \leq 0 \quad \forall s \in \mathbb{R}^+$
- (h4) $\mu'(s) + \delta\mu(s) \leq 0 \quad \forall s \in \mathbb{R}^+ \quad \text{and some } \delta > 0$
- (h5) $k(s) \leq M\mu(s) \quad \forall s \in \mathbb{R}^+ \quad \text{and some } M > 0.$

It is readily seen that a kernel of the form $k(s) = k_0 \exp[-\alpha_0 s]$ fulfills (h1)–(h5), for every $\alpha < \alpha_0$. In this case $M = 1/(\alpha_0 - \alpha)$ and $\delta = \alpha$.

We remark that condition (h4), which is not actually needed in the existence and uniqueness results that follow, implies the exponential decay of $\mu(s)$. Nonetheless, it allows $\mu(s)$ to have a singularity at $s = 0$, whose order is less than 1.

The aim of this paper is the analysis of the asymptotic behavior of the solution of (1.1) together with its past history. For this reason, along the line of [2], we introduce a new variable which embodies the past history of the equation, namely

$$\eta^t(x, s) = u(x, t) - u(x, t - s), \quad s \in \mathbb{R}^+. \tag{1.5}$$

As a consequence, (1.2) reads

$$u_t - \beta \Delta u + \int_0^\infty k(\sigma) \Delta \eta(\sigma) d\sigma + g(u) = f \tag{1.6}$$

In order to focus on the dissipative and antidissipative terms of the problem, we need to handle a second order version of (1.6). This is achieved by substituting (1.5) into (1.3). Indeed, recalling that $k(0) = -\int_0^\infty k'(\sigma) d\sigma$, we have

$$u_{tt} + \int_0^\infty k'(\sigma) \Delta \eta(\sigma) d\sigma + g'(u)u_t = f_t. \tag{1.7}$$

Then, addition of (1.7) and α -times (1.6) leads to the system

$$\begin{cases} u_{tt} = \alpha\beta\Delta u - \alpha u_t \\ \quad + \int_0^\infty \mu(\sigma) \Delta \eta(\sigma) d\sigma - \alpha g(u) - g'(u)u_t + \alpha f + f_t \\ \eta_t = -\eta_s + u_t. \end{cases} \tag{1.8}$$

The second equation, needed to close the above system, is obtained differentiating (1.5).

Boundary and initial conditions are then translated into

$$\begin{cases} u(x, t) = 0 & x \in \partial\Omega, \quad t \geq 0 \\ \eta^t(x, s) = 0 & (x, s) \in \partial\Omega \times \mathbb{R}^+, \quad t \geq 0 \end{cases} \tag{1.9}$$

and

$$\begin{cases} u(x, 0) = u_0(x) & x \in \Omega \\ u_t(x, 0) = v_0(x) & x \in \Omega \\ \eta^0(x, s) = \eta_0(x, s) & (x, s) \in \Omega \times \mathbb{R}^+ \end{cases}$$

where we set

$$\begin{cases} u_0(x) = u_0(x, 0) \\ v_0(x) = \partial_t u_0(x, t)|_{t=0} \\ \eta_0(x, s) = u_0(x, 0) - u_0(x, -s). \end{cases}$$

Existence, uniqueness and asymptotic behavior for the linear problem associated to (1.1), subject to initial-boundary conditions, have been investigated by several authors (e.g., [7, 8, 11, 12]). In particular, in [7], we proved the

exponential stability of the system along with the past summed history via semi-group techniques. The parabolic analogue to (1.1), obtained when k has a Dirac delta distribution at the origin, has been considered in [5, 6], where we proved also the existence of a uniform attractor for the solutions.

The plan of the paper is as follows. In Section 2 we describe the functional setting. Section 3 is devoted to existence and uniqueness results. Finally, in Section 4, we prove the existence of a uniform absorbing set for the solutions.

2 The functional setting

Let $\Omega \subset \mathbb{R}^3$ be a bounded domain with smooth boundary. With usual notation, we introduce the spaces L^p , $W^{k,p}$, $H^k = W^{k,2}$ and H_0^k acting on Ω . Throughout the paper, we denote by c a generic positive constant (which may vary even in the same line). Given a space \mathcal{X} , we denote its norm by $\|\cdot\|_{\mathcal{X}}$ and its inner product by $\langle \cdot, \cdot \rangle_{\mathcal{X}}$ (summation on the components is understood when we have vectorial quantities). When $\mathcal{X} = L^2$ we omit the subscript. The symbol $\langle \cdot, \cdot \rangle$ will be also used to denote the duality map between H^{-1} and H_0^1 or between L^p and L^q . We will also consider spaces of \mathcal{X} -valued functions defined on an (possibly infinite) interval I such as $C(I, \mathcal{X})$, $L^p(I, \mathcal{X})$ and $W^{k,p}(I, \mathcal{X})$, with the usual norms. In force of Poincaré inequality

$$\|u\|^2 \leq \lambda_0 \|\nabla u\|^2 \quad \forall u \in H_0^1 \tag{2.1}$$

(for some $\lambda_0 > 0$) the inner product in H_0^1 will be chosen to be

$$\langle \cdot, \cdot \rangle_{H_0^1} = \langle \nabla \cdot, \nabla \cdot \rangle.$$

In view of (h1)–(h2), let $\mathcal{M} = L^2_{\mu}(\mathbb{R}^+, H_0^1)$ be the Hilbert space of H_0^1 -valued functions on \mathbb{R}^+ , endowed with the inner product

$$\langle \varphi, \psi \rangle_{\mathcal{M}} = \int_0^{\infty} \mu(\sigma) \langle \nabla \varphi(\sigma), \nabla \psi(\sigma) \rangle d\sigma.$$

Finally we introduce the Hilbert space

$$\mathcal{H} = H_0^1 \times L^2 \times \mathcal{M}.$$

To describe the asymptotic behavior of the solutions of our system we need also to introduce the Banach space \mathcal{T} of $W_{loc}^{1,1}$ -translation bounded L^2 -valued functions on \mathbb{R}^+ , namely

$$\mathcal{T} = \left\{ f \in W_{loc}^{1,1}(\mathbb{R}^+, L^2) : \|f\|_{\mathcal{T}} = \sup_{\xi \geq 0} \int_{\xi}^{\xi+1} \|f(y)\| + \|f'(y)\| dy < \infty \right\}.$$

We conclude the section with a slight generalization of Lemma A.3 in [14].

Lemma 2.1 *Let $h \in C(\mathbb{R})$ satisfy $|h(u)| \leq c(1 + |u|^p)$, for some $c > 0$ and some $p \geq 0$, and let X be a bounded Lebesgue measurable subset of \mathbb{R}^n . Then for every $q \geq \max\{1, 2p\}$, and every $r \geq 0$ h is a continuous mapping from $L^{q+2r}(X)$ to $L^{2+r}(X)$.*

3 Existence and uniqueness

We assume that the nonlinear term g is a continuously differentiable function on \mathbb{R} . Moreover, there exist $c_1, c_2 > 0$ and $0 \leq p < 2$ such that

$$\begin{aligned} \text{(g1)} \quad & g'(y) \geq -c_1 \\ \text{(g2)} \quad & |g'(y)| \leq c_2(1 + |y|^p). \end{aligned}$$

Remark 3.1 Let us rewrite the first equation in (1.8) as follows:

$$u_{tt} + (\alpha + g'(u))u_t - \alpha\beta\Delta u = \int_0^\infty \mu(\sigma)\Delta\eta(\sigma) d\sigma - \alpha g(u) + \alpha f + f_t. \quad (3.1)$$

If the constant c_1 in (g1) satisfies

$$c_1 < \alpha \quad (3.2)$$

then it is apparent that

$$\inf_{y \in \mathbb{R}} (\alpha + g'(y)) > 0$$

and the damping term in the left-hand side of (3.1) furnishes a significant (and non-degenerate) contribution to energy dissipation. Notice that condition (3.2) is not used to prove existence and uniqueness results. Nevertheless, it plays a crucial role in the proof of the existence of uniform absorbing sets.

Definition 3.2 Let (h1)–(h2) hold. Set $I = [0, T]$, for $T > 0$, and let $f \in W^{1,1}(I, L^2)$. We say a function $(u, u_t, \eta) \in C(I, \mathcal{H})$ is a solution to problem (1.8)–(1.9) in the time interval I , with initial data $(u_0, v_0, \eta_0) \in \mathcal{H}$, provided

$$\begin{aligned} \langle u_{tt}, w \rangle &= -\alpha\beta\langle \nabla u, \nabla w \rangle - \alpha\langle u_t, w \rangle - \int_0^\infty \mu(\sigma)\langle \nabla\eta(\sigma), \nabla w \rangle d\sigma \\ &\quad - \alpha\langle g(u), w \rangle - \langle g'(u)u_t, w \rangle + \alpha\langle f, w \rangle + \langle f_t, w \rangle \\ \langle \eta_t + \eta_s, \varphi \rangle_{\mathcal{N}} &= \langle u_t, \varphi \rangle_{\mathcal{N}} \end{aligned} \quad (3.2)$$

for all $w \in H_0^1$, $\varphi \in \mathcal{N}$, and a.e. $t \in I$, where we set $\mathcal{N} = L_\mu^2(\mathbb{R}^+, L^2)$. Here, $-\eta_s$ is interpreted as the infinitesimal generator of the right-translation semigroup on \mathcal{M} .

We now state and prove existence and uniqueness results.

Theorem 3.3 (Existence). *Let (h1)–(h3) and (g1)–(g2) hold. Then, given any $T > 0$, problem (1.8)–(1.9) has a solution (u, u_t, η) in the time interval $I = [0, T]$, with initial data (u_0, v_0, η_0) .*

Proof. The theorem is proved re-casting exactly the Faedo-Galerkin scheme used in [5]. Uniform estimates for the approximate solutions are obtained as in the proof of the following Theorem 4.2. Actually the situation here is much simpler, since the nonlinear terms are controlled observing that, for every $u \in H_0^1$ and $v \in L^2$,

$$\langle g'(u)v, v \rangle \geq -c_1 \|v\|^2$$

and

$$|\langle g(u), v \rangle| \leq \|g(u)\| \|v\| \leq c(1 + \|\nabla u\|^2 + \|v\|^2)$$

in force of (g1)–(g2) and Young inequality. Thus, for a sequence of approximate solutions (u_n, η_n) , one gets the uniform bound

$$\|u_n\|_{L^\infty(I, H_0^1) \cap W^{1, \infty}(I, L^2)} \leq c.$$

Notice that, since $f \in W^{1,1}(I, L^2)$, a generalized Gronwall lemma in the differential form is required (see, e.g., Lemma A.1 in [14]). Concerning passage to limit, the only problem is the nonlinear term $\alpha g(u) - g'(u)u_t$. Exploiting classical compact embeddings (recall that $p < 2$) we conclude that, up to a subsequence,

$$u_n \longrightarrow u \quad \text{strongly in } L^{2(p+1)}(I \times \Omega). \tag{3.4}$$

Moreover,

$$\partial_t u_n \longrightarrow u_t \quad \text{weakly in } L^2(I \times \Omega). \tag{3.5}$$

Therefore, in virtue of (g2) and (3.4), applying Lemma 2.1 we get the convergences

$$g(u_n) \longrightarrow g(u) \quad \text{strongly in } L^2(I \times \Omega) \tag{3.6}$$

and

$$g'(u_n) \longrightarrow g'(u) \quad \text{strongly in } L^3(I \times \Omega). \tag{3.7}$$

Let now $w \in H_0^1$. From (3.6) it is apparent that

$$\langle g(u_n), w \rangle \longrightarrow \langle g(u), w \rangle.$$

Convergence (3.7) entails

$$g'(u_n)w \longrightarrow g'(u)w \quad \text{strongly in } L^2(I \times \Omega)$$

which, together with (3.5), gives

$$\langle g'(u_n)\partial_t u_n, w \rangle \longrightarrow \langle g'(u)u_t, w \rangle.$$

Continuity in time of u and u_t follows from usual arguments (cf. [4]). Continuity of η follows consequently, as in the proof of Theorem 3.2 in [15]. \square

Theorem 3.4 (Uniqueness). *Let (h1)–(h3) and (g1)–(g2) hold. Then, given any $T > 0$, the solution (u, u_t, η) to (1.8)–(1.9) in the time interval $I = [0, T]$, with initial data (u_0, v_0, η_0) is unique.*

Proof. For $i = 1, 2$, let $z_i = (u_i, \partial_t u_i, \eta_i)$ be two solutions of (1.8)–(1.9) with initial data $z_0 = (u_0, v_0, \eta_0)$, and denote $z = (u, u_t, \eta) = z_1 - z_2$, with $z(0) = (0, 0, 0)$. Adding and subtracting in (1.8) we obtain

$$\begin{aligned} u_{tt} &= \alpha\beta\Delta u - \alpha u_t + \int_0^\infty \mu(\sigma)\Delta\eta(\sigma) d\sigma - \alpha[g(u_1) - g(u_2)] \\ &\quad - \partial_t[g(u_1) - g(u_2)] \\ \eta_t &= -\eta_s + u_t. \end{aligned} \tag{3.8}$$

Fix then $\tau \in (0, T]$, and define

$$v(t) = \begin{cases} \int_t^\tau u(y) dy & 0 \leq t \leq \tau \\ 0 & \tau \leq t \leq T. \end{cases}$$

Moreover, let

$$\tilde{u}(t) = \int_0^t u(y) dy \quad \text{and} \quad \tilde{\eta}^t = \int_0^t \eta^y dy.$$

Notice that, for every $t \in I$, $v(t) \in H_0^1$, $\tilde{u}(t) \in H_0^1$, $\tilde{\eta}^t \in \mathcal{M}$, and $v(\tau) = \tilde{u}(0) = \tilde{\eta}^0 = 0$. Finally, $v_t = -u$, $\tilde{u}_t = u$, and $\tilde{\eta}_t = \eta$. Take the duality product of (3.8) with $v(t)$, and integrate in time from 0 to τ . Thanks to the above conditions, repeated integrations by parts lead to

$$\begin{aligned} &\frac{1}{2}(\|u(\tau)\|^2 + \alpha\beta\|\nabla\tilde{u}(\tau)\|^2) + \alpha \int_0^\tau \|u(t)\|^2 dt \\ &= - \int_0^\tau \langle \tilde{\eta}^t, u(t) \rangle_{\mathcal{M}} dt - \alpha \int_0^\tau \langle g(u_1(t)) - g(u_2(t)), v(t) \rangle dt \\ &\quad - \int_0^\tau \langle g(u_1(t)) - g(u_2(t)), u(t) \rangle dt. \end{aligned} \tag{3.10}$$

In force of (g2), and the fact that $u_i \in L^\infty(I, H_0^1)$, we get

$$\|g(u_1) - g(u_2)\|_{L^{6/5}} \leq \|c_2(1 + |u_1|^p + |u_2|^p)\|_{L^3} \|u\| \leq c\|u\|.$$

Also, observe that

$$\begin{aligned} \int_0^\tau \|\nabla v(t)\|^2 dt &= \int_0^\tau \|\nabla\tilde{u}(\tau) - \nabla\tilde{u}(t)\|^2 dt \\ &\leq 2\tau\|\nabla\tilde{u}(\tau)\|^2 + 2 \int_0^\tau \|\nabla\tilde{u}(t)\|^2 dt. \end{aligned}$$

Therefore, the continuous embedding $L^{6/5} \hookrightarrow H^{-1}$, Hölder inequality, and Young inequality, entail

$$\begin{aligned}
 & -\alpha \int_0^\tau \langle g(u_1(t)) - g(u_2(t)), v(t) \rangle dt \\
 & \leq \alpha \int_0^\tau \|g(u_1(t)) - g(u_2(t))\|_{H^{-1}} \|\nabla v(t)\| dt \\
 & \leq c \int_0^\tau \|u(t)\| \|\nabla v(t)\| dt \\
 & \leq \frac{\alpha\beta}{4} \|\nabla \tilde{u}(\tau)\|^2 + c \int_0^\tau \|\nabla \tilde{u}(t)\|^2 dt + c \int_0^\tau \|u(t)\|^2 dt. \tag{3.11}
 \end{aligned}$$

Concerning the last term of (3.10), condition (g1) yields

$$- \int_0^\tau \langle g(u_1(t)) - g(u_2(t)), u(t) \rangle dt \leq c_1 \int_0^\tau \|u(t)\|^2 dt. \tag{3.12}$$

We now integrate equality (3.9) from 0 to t , to get

$$\eta^t + \tilde{\eta}_s^t = u(t).$$

Taking the inner product in \mathcal{M} of the above equation and $\tilde{\eta}^t$, and integrating in time from 0 to τ , we have

$$\int_0^\tau \langle \eta^t + \tilde{\eta}_s^t, \tilde{\eta}^t \rangle_{\mathcal{M}} dt = \int_0^\tau \langle u(t), \tilde{\eta}^t \rangle_{\mathcal{M}} dt. \tag{3.13}$$

Exploiting (h3), integration by parts, and an approximation argument (cf. [5,15]) the integrand of the left-hand side of (3.13) is seen to satisfy

$$\langle \eta^t + \tilde{\eta}_s^t, \tilde{\eta}^t \rangle_{\mathcal{M}} = \langle \tilde{\eta}_t^t + \tilde{\eta}_s^t, \tilde{\eta}^t \rangle_{\mathcal{M}} \geq \frac{1}{2} \frac{d}{dt} \|\tilde{\eta}^t\|_{\mathcal{M}}^2$$

and (3.13) turns into

$$\frac{1}{2} \|\tilde{\eta}^\tau\|_{\mathcal{M}}^2 \leq \int_0^\tau \langle u(t), \tilde{\eta}^t \rangle_{\mathcal{M}} dt. \tag{3.14}$$

Finally, addition of (3.10) and (3.14), with the aid of (3.11)–(3.13), entails

$$\|u(\tau)\|^2 + \|\nabla \tilde{u}(\tau)\|^2 + \|\tilde{\eta}^\tau\|_{\mathcal{M}}^2 \leq c \int_0^\tau \|u(t)\|^2 dt + c \int_0^\tau \|\nabla \tilde{u}(t)\|^2 dt$$

and Gronwall lemma in the integral form implies that $u(\tau) = \tilde{\eta}^\tau = 0$. Since τ is arbitrary, we conclude that $(u(t), v(t), \eta^t) = (0, 0, 0)$ for every $t \in I$. \square

Remark 3.5 For the solution $z = (u, u_t, \eta)$ with initial data z_0 of (1.8)–(1.9) define

$$\mathcal{U}z(t) = u_t(t) - \beta \Delta u(t) + \int_0^\infty k(\sigma) \Delta \eta^t(\sigma) d\sigma + g(u(t)) - f(t)$$

When (h5) holds too, by Lemma 2.1 we get the continuity $\mathcal{U}z \in C(I, H^{-1})$. In particular, $\mathcal{U}z(0) = \mathcal{U}z_0$. Since by definition

$$\partial_t \mathcal{U}z + \alpha \mathcal{U}z = 0$$

we conclude that

$$\mathcal{U}z(t) = \mathcal{U}z_0 e^{-\alpha t}.$$

Thus z solves (1.6) provided that $\mathcal{U}z_0 = 0$. This condition is not really a constraint on the initial data; indeed equation (1.6) is of the first order in time, and the initial value of u_t is automatically determined by the equation. Conversely, every $z \in C(I, \mathcal{H})$ which solves (1.6) is a solution of (1.8)–(1.9). Hence, given $u_0 \in H_0^1$ and $\eta_0 \in \mathcal{M}$ there is a unique solution $z \in C(I, \mathcal{H})$ of (1.6) if and only if the vector v_0 determined by the equation $\mathcal{U}(u_0, v_0, \eta_0) = 0$ belongs to L^2 .

In the sequel, we agree to denote the solution $z(t)$ of (1.8)–(1.9) with initial data z_0 by $S(t)z_0$. In force of the existence and continuous dependence results, the one-parameter family of operators $S(t)$ enjoys the following properties:

- (i) $S(0)$ is the identity map on \mathcal{H}
- (ii) $S(t)z \in C([0, \infty), \mathcal{H})$ for any $z \in \mathcal{H}$.

When the system is autonomous (f independent of time) $S(t)$ fulfills also

- (iii) $S(t)S(\tau) = S(t + \tau)$ for any $t, \tau \geq 0$.

We remark that $S(t)$ might not be a C_0 -semigroup of continuous (nonlinear) operators on \mathcal{H} , since the continuity $S(t) \in C(\mathcal{H}, \mathcal{H})$ for any $t \geq 0$, in general, does not hold, unless we are in the simpler situation when g is Lipschitz.

Theorem 3.6 *Let (h1)–(h3) and (g1)–(g2) with $p = 0$ hold (that is, g is Lipschitz). Then $S(t) \in C(\mathcal{H}, \mathcal{H})$ for any $t \geq 0$. In particular, if f is independent of time, $S(t)$ is a C_0 -semigroup.*

Proof. Let $z_{0n} \in \mathcal{H}$ be a sequence converging in \mathcal{H} to $z_{0\infty} \in \mathcal{H}$. Denote by $z_n = (u_n, \partial_t u_n, \eta_n)$ and $z_\infty = (u_\infty, \partial_t u_\infty, \eta_\infty)$ the corresponding solutions to (1.8)–(1.9). Finally, let $\bar{z}_{0n} = z_{0n} - z_{0\infty}$ and $\bar{z}_n = z_n - z_\infty = (\bar{u}_n, \partial_t \bar{u}_n, \bar{\eta}_n)$. Again, we add and subtract in (1.8), and we multiply the two resulting equation by $\partial_t \bar{u}_n$ in L^2 , and by $\bar{\eta}_n$ in \mathcal{M} , respectively. Clearly, the multiplications make sense for Faedo-Galerkin approximants. However, due to the uniqueness result, the final estimates hold to the limit. Adding the results, and exploiting the inequality

$$\langle g'(u_n) \partial_t u_n - g'(u_\infty) \partial_t u_\infty, \partial_t \bar{u}_n \rangle \leq c \|\partial_t u_n\|^2 + c \|(g'(u_n) - g'(u_\infty)) \partial_t u_\infty\|^2$$

we easily obtain

$$\frac{d}{dt} \|\bar{z}_n\|_{\mathcal{H}}^2 \leq c \|\bar{z}_n\|_{\mathcal{H}}^2 + c \|(g'(u_n) - g'(u_\infty))\partial_t u_\infty\|^2.$$

An immediate generalization of Theorem 3.4 (i.e., taking different initial data) shows that, as $z_{0n} \rightarrow z_{0\infty}$ in \mathcal{H} , the convergence $u_n \rightarrow u_\infty$ holds in $L^2(I \times \Omega)$. Hence, there exists a subsequence $u_{n_k} \rightarrow u_\infty$ a.e. in $I \times \Omega$. Setting $\psi_k = (g'(u_{n_k}) - g'(u_\infty))\partial_t u_\infty$, we have that

$$\varepsilon_k = \int_0^T \int_\Omega |\psi_k|^2 dx dt \longrightarrow 0 \quad (k \rightarrow \infty)$$

by virtue of the Lebesgue dominated convergence theorem. Thus Gronwall lemma applied to the subsequence \bar{z}_{n_k} yields

$$\|\bar{z}_{n_k}(t)\|_{\mathcal{H}}^2 \leq e^{cT} \|\bar{z}_{0n_k}\|_{\mathcal{H}}^2 + ce^{cT} \varepsilon_k$$

for any $t \in I$. We conclude that, whenever $z_{0n} \rightarrow z_{0\infty}$ in \mathcal{H} , there exists a subsequence z_{0n_k} such that $S(t)z_{0n_k} \rightarrow S(t)z_{0\infty}$ for all $t \in I$. Using an immediate contradiction argument, this implies that $S(t)z_{0n} \rightarrow S(t)z_{0\infty}$ for any $t \in I$. Being T arbitrary, we proved that $S(t) \in C(\mathcal{H}, \mathcal{H})$ for any $t \geq 0$. \square

4 Existence of uniform absorbing sets

An *absorbing set* for $S(t)$ is a bounded set $\mathcal{B}_0 \subset \mathcal{H}$ such that for any bounded set $\mathcal{B} \subset \mathcal{H}$ there exists a time $t^* = t^*(\mathcal{B})$ such that

$$S(t)\mathcal{B} \subset \mathcal{B}_0 \quad \forall t \geq t^*.$$

To stress the dependence of $S(t)$ on the given external term f , we shall write $S_f(t)$. The aim of this section is to prove the existence of an absorbing set for $S_f(t)$, which is uniform as f is allowed to run in a certain functional set. In order to accomplish that, we are required to ask stronger conditions both on the nonlinear term and on the memory kernel.

Concerning the nonlinear term, setting

$$G(y) = \int_0^y g(\xi) d\xi$$

we assume that the following hold (cf. [4]):

$$\begin{aligned} \text{(g3)} \quad & \liminf_{|y| \rightarrow \infty} \frac{G(y)}{y^2} \geq 0 \\ \text{(g4)} \quad & \liminf_{|y| \rightarrow \infty} \frac{yg(y) - c_3 G(y)}{y^2} \geq 0 \end{aligned}$$

for some $c_3 > 0$. There is no loss of generality if we assume $c_3 \leq \alpha\beta/2$. These conditions are fulfilled by many classical examples, such as $g(u) = |u|^p u - \gamma u$ or $g(u) = \sin u$ (see [16]). For $u \in H_0^1$, denote

$$\mathcal{G}(u) = \int_{\Omega} G(u(x)) \, dx.$$

The easy proof of next lemma is left to the reader.

Lemma 4.1 *Assume (g3)–(g4). Then for every $\nu > 0$ there exist $c(\nu) > 0$ such that*

$$\mathcal{G}(u) \geq -\nu \|\nabla u\|^2 - c(\nu) \tag{4.1}$$

$$\langle g(u), u \rangle \geq -\nu \|\nabla u\|^2 - c(\nu) \tag{4.2}$$

$$\langle g(u), u \rangle - c_3 \mathcal{G}(u) \geq -\nu \|\nabla u\|^2 - c(\nu) \tag{4.3}$$

for all $u \in H_0^1$.

Theorem 4.2 *Assume (h1)–(h4), (g1)–(g4), and (3.2) (cf. Remark 3.1). Let $\mathcal{F} \subset \mathcal{T}$ be a bounded set. Then there exists an absorbing set for $S_f(t)$ which is uniform as $f \in \mathcal{F}$.*

Proof. For every $r > 0$, let $\mathcal{B}(r)$ be the ball of \mathcal{H} of radius r centered in the origin. Moreover, denote

$$M_0 = \sup_{h \in \mathcal{F}} \|h\|_{\mathcal{T}}.$$

Fix then $R > 0$, and let $f \in \mathcal{F}$ and $z_0 \in \mathcal{B}(R)$. For any $0 < \varepsilon \leq \alpha/2$, introduce the new variable $w = u_t + \varepsilon u$; then multiply the first equation of (1.8) by w in \mathcal{H} , and the second one by η in \mathcal{M} , where $(u(t), u_t(t), \eta^t) = S_f(t)z_0$. Clearly, the multiplication makes sense in a Faedo-Galerkin scheme. So we get

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} (\alpha\beta \|\nabla u\|^2 + \|w\|^2 + 2(\alpha - \varepsilon)\mathcal{G}(u) + 2\varepsilon \langle g(u), u \rangle) \\ & + \varepsilon\alpha\beta \|\nabla u\|^2 + (\alpha - \varepsilon)\|w\|^2 = - \int_0^\infty \mu(\sigma) \langle \nabla \eta(\sigma), \nabla u_t \rangle \, d\sigma - \varepsilon \\ & \int_0^\infty \mu(\sigma) \langle \nabla \eta(\sigma), \nabla u \rangle \, d\sigma - \varepsilon\alpha \langle g(u), u \rangle \\ & - \langle g'(u)u_t, u_t \rangle + \varepsilon(\alpha - \varepsilon)\langle u, w \rangle + \alpha \langle f, w \rangle + \langle f_t, w \rangle \end{aligned} \tag{4.4}$$

and

$$\frac{1}{2} \frac{d}{dt} \|\eta\|_{\mathcal{M}}^2 + \frac{\delta}{2} \|\eta\|_{\mathcal{M}}^2 \leq \int_0^\infty \mu(\sigma) \langle \nabla \eta(\sigma), \nabla u_t \rangle \, d\sigma. \tag{4.5}$$

The above inequality (4.5) is obtained integrating by parts the term

$$\int_0^\infty \mu(\sigma) \langle \nabla \eta_s(\sigma), \nabla \eta(\sigma) \rangle \, d\sigma = \frac{1}{2} \int_0^\infty \mu(\sigma) \frac{d}{ds} \|\nabla \eta(\sigma)\|^2 \, d\sigma$$

and using (h4) (see [5] for more details). Setting $c_4 = \|\mu\|_{L^1(\mathbb{R}^+)}/\delta$, Young inequality entails

$$-\varepsilon \int_0^\infty \mu(\sigma) \langle \nabla \eta(\sigma), \nabla u \rangle d\sigma \leq \varepsilon^2 c_4 \|\nabla u\|^2 + \frac{\delta}{4} \|\eta\|_{\mathcal{M}}^2. \tag{4.6}$$

Denote

$$\tau = \tau(\varepsilon) = \frac{\alpha}{\alpha - \varepsilon + \varepsilon c_3}.$$

Notice that $0 < \tau \leq 2$. In particular we see that $\alpha\beta \geq \tau c_3$. Making use of (4.3), with $\nu = \beta/4$,

$$\begin{aligned} -\varepsilon\alpha \langle g(u), u \rangle &= -\varepsilon\tau(\alpha - \varepsilon) \langle g(u), u \rangle - \varepsilon^2 \tau c_3 \langle g(u), u \rangle \\ &\leq -\varepsilon\tau c_3(\alpha - \varepsilon) \mathcal{G}(u) - \varepsilon^2 \tau c_3 \langle g(u), u \rangle + \frac{\varepsilon\alpha\beta}{4} \|\nabla u\|^2 + c_5 \end{aligned} \tag{4.7}$$

with $c_5 = \alpha^2 c(\beta/4)$. Condition (g1), (2.1), and Young inequality, entail

$$\begin{aligned} &-\langle g'(u)u_t, u_t \rangle + \varepsilon(\alpha - \varepsilon) \langle u, w \rangle \\ &\leq c_1 \|u_t\|^2 + \varepsilon\alpha \|u\| \|w\| \\ &\leq c_1 \|w\|^2 + \varepsilon^2 c_1 \|u\|^2 + \varepsilon(2c_1 + \alpha) \|u\| \|w\| \\ &\leq \left(c_1 + \frac{\sqrt{\varepsilon}(2c_1 + \alpha)}{2} \right) \|w\|^2 + \varepsilon\sqrt{\varepsilon}\lambda_0 \left(\frac{2c_1 + \alpha + \alpha\sqrt{2\alpha}}{2} \right) \|\nabla u\|^2. \end{aligned} \tag{4.8}$$

Finally,

$$\alpha \langle f, w \rangle + \langle f_t, w \rangle \leq (\alpha + 1)(\|f\| + \|f_t\|) \|w\|. \tag{4.9}$$

Due to (4.1)–(4.2) it is apparent that there exist $c_6 > 0$ such that, defining

$$\Phi^2 = \alpha\beta \|\nabla u\|^2 + \|w\|^2 + \|\eta\|_{\mathcal{M}}^2 + 2(\alpha - \varepsilon) \mathcal{G}(u) + 2\varepsilon \langle g(u), u \rangle + c_6$$

the relation

$$\Phi^2 \geq c_7 \|S_f(t)z_0\|^2 \tag{4.10}$$

holds for some $c_7 > 0$ and every ε small enough. Moreover, from (g2), there exists $\Lambda(r) > 0$ such that

$$\Phi^2(0) \leq \Lambda(r) \quad \text{whenever} \quad \|z_0\|_{\mathcal{H}}^2 \leq r. \tag{4.11}$$

Choose now $\varepsilon \leq \alpha/2$ small enough such that (4.10) and the following inequalities hold:

$$\frac{\delta}{2} \geq \varepsilon\tau c_3 \tag{4.12}$$

$$\frac{3\alpha\beta}{4} - \varepsilon c_4 - \sqrt{\varepsilon}\lambda_0 \left(\frac{2c_1 + \alpha + \alpha\sqrt{2\alpha}}{2} \right) \geq \frac{\tau c_3}{2} \tag{4.13}$$

and

$$\alpha - c_1 - \varepsilon - \frac{\sqrt{\varepsilon}(2c_1 + \alpha)}{2} \geq \frac{\varepsilon\tau c_3}{2}. \quad (4.14)$$

Hence, setting

$$\varepsilon_0 = \varepsilon\tau c_3 \quad \text{and} \quad c_8 = 2c_5 + \varepsilon_0 c_6$$

adding (4.4)–(4.5), and collecting (4.6)–(4.9) and (4.12)–(4.14), we are led to

$$\frac{d}{dt}\Phi^2 + \varepsilon_0\Phi^2 \leq c_8 + (\alpha + 1)(\|f\| + \|f_t\|)\Phi. \quad (4.15)$$

Applying a generalization of Gronwall lemma to (4.15) (see, for instance, [14, 15]), we get the inequality

$$\Phi^2(t) \leq 2\Phi^2(0)e^{-\varepsilon_0 t} + C(M_0) \quad \forall t \in \mathbb{R}^+ \quad (4.16)$$

where

$$C(M_0) = \frac{2c_8}{\varepsilon_0} + \frac{e^{\varepsilon_0} M_0^2 (\alpha + 1)^2}{(1 - e^{-\varepsilon_0/2})^2}.$$

Therefore from (4.10)–(4.11) and (4.16),

$$\|S_f(t)z_0\|_{\mathcal{H}}^2 \leq \frac{2\Lambda(R^2)}{c_7} e^{-\varepsilon_0 t} + \frac{C(M_0)}{c_7} \quad \forall t \in \mathbb{R}^+$$

and this relation holds for every $z_0 \in \mathcal{B}(R)$ and $f \in \mathcal{F}$. Setting

$$\mathcal{B}_0 = \mathcal{B}(\sqrt{2C(M_0)/c_7})$$

and

$$t^* = t^*(R) = \max \left\{ \frac{1}{\varepsilon_0} \log \left[\frac{C(M_0)}{2\Lambda(R^2)} \right], 0 \right\}$$

we conclude that

$$\bigcup_{f \in \mathcal{F}} S_f(t)\mathcal{B}(R) \subset \mathcal{B}_0 \quad \forall t \geq t^*$$

as desired. □

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